

Beware of Typos!

(1)

<sup>OPPENHEIM.</sup>  
FILTER DESIGN METHODS (CHAPTER 7)

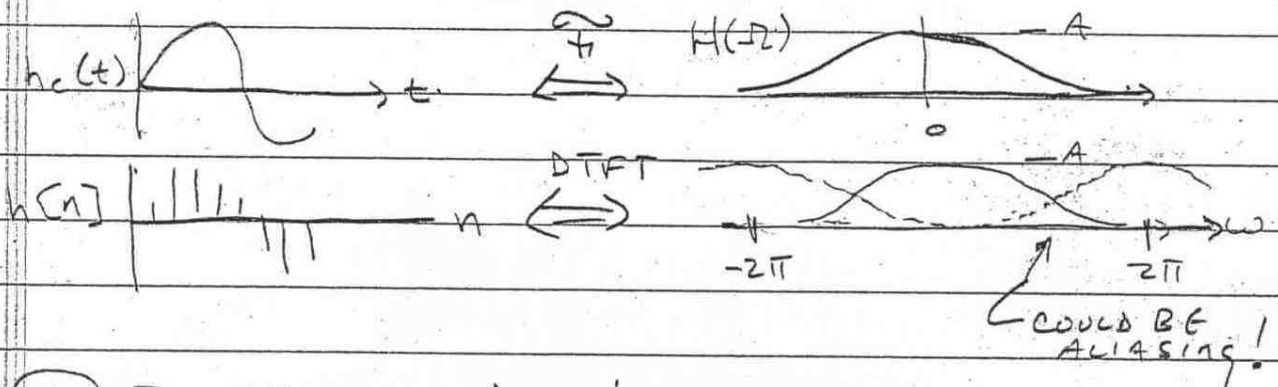
GENERALLY START WITH SOME ANALOG FILTER DESIGN,  $h_c(t)$  or  $H_c(s)$ , AND SOMEHOW CONVERT THIS TO A DIGITAL FILTER,  $h[n]$  OR  $H(z)$ .

① IMPULSE INVARIANCE METHOD

①A IN TIME DOMAIN:

→  $h[n] = T_s h_c(nT_s)$

i.e. SAMPLE THE CONTINUOUS IMPULSE RESPONSE AT  $T_s$ .



①B IN FREQUENCY DOMAIN:

SOMETIMES WE WANT TO DESIGN THE DIGITAL FILTER FROM THE LAPLACE TRANSFORM OF THE ANALOG FILTER,  $\mathcal{L}\{h_c(t)\} = H_c(s)$ .

DERIVATION OF THE METHOD!

FIRST:

SUPPOSE  $H_c(s) = \sum_{k=1}^N \frac{A_k}{s - s_k}$  (PARTIAL FRACTION EXPANSION)

then

$h_c(t) = \mathcal{L}^{-1}\{H_c(s)\} = \sum_{k=1}^N A_k e^{s_k t}$

then

$h[n] = T_s h_c(nT_s) = T_s \sum_{k=1}^N A_k e^{s_k nT_s}$

SECOND:

$$Z\{h[n]\} = Z\left\{T_s \sum_{k=-1}^N A_k e^{s_k n T_s}\right\}$$

$$= \sum_{n=-\infty}^{\infty} T_s \sum_{k=-1}^N A_k e^{s_k n T_s} z^{-n}$$

$$= \sum_{k=-1}^N A_k T_s \sum_{n=-\infty}^{\infty} (e^{s_k T_s} z^{-1})^n$$

$$H(z) = \sum_{k=-1}^N \frac{A_k T_s}{1 - e^{s_k T_s} z^{-1}}$$

So:

$$\text{Given } H_c(s) = \sum_{k=-1}^N \frac{A_k}{s - s_k}$$

$$H(z) = \sum_{k=-1}^N \frac{A_k T_s}{1 - e^{s_k T_s} z^{-1}}$$

← FREQ. DOMAIN  
VERSION OF  
IMPULSE INVARIANCE  
METHOD.

## ② BILINEAR TRANSFORM

- RECALL, IMPULSE INVARIANCE HAS ALIASING.
- BILINEAR TRANSFORM AVOIDS ALIASING BY "SQUEEZING"  $-\infty < \Omega < \infty$  INTO  $-\pi < \omega < \pi$
- IT IS A FREQUENCY DOMAIN METHOD.

\* → GIVEN ANALOG FILTER  $H_c(s)$

$$H(z) = H_c(s) \Big|_{s = \frac{z}{T_s} \left( \frac{z-1}{z+1} \right) = \frac{z}{T_s} \left( \frac{1-z^{-1}}{1+z^{-1}} \right)}$$

USE EITHER FORM.

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## IMPORTANT ASPECTS OF BILINEAR TRANSFORM.

- No Aliasing
- Stable analog filter guarantees stable  $H(z)$
- Frequency warping

Since the  $-\infty \rightarrow \infty$  continuous frequency is mapped into  $-\pi \rightarrow \pi$  discrete-time frequency, something must be "warped" or "squeezed"

Let  $s = \sigma + j\Omega$ ;  $z = r e^{j\omega}$   
then the substitution becomes.

$$s = \frac{z}{T_s} \left( \frac{z-1}{z+1} \right)$$

becomes  $\sigma + j\Omega = \left( \frac{z}{T_s} \right) \left( \frac{r e^{j\omega} - 1}{r e^{j\omega} + 1} \right)$

After much rearrangement:

$$\sigma = \frac{z}{T_s} \frac{r^2 - 1}{1 + r^2 + 2r \cos(\omega)} \quad \Omega = \frac{z}{T_s} \frac{2r \sin(\omega)}{1 + r^2 + 2r \cos(\omega)}$$

Of particular interest is the unit circle in  $z$ -plane where  $r=1$ ; then  $\sigma=0$ , and

$$\begin{aligned} \Omega &= \frac{z}{T_s} \frac{\sin(\omega)}{1 + \cos(\omega)} = \frac{z}{T_s} \frac{\sin(\omega)}{2 \cos^2(\omega/2)} = \frac{z}{T_s} \frac{\sin(\omega/2) \cos(\omega/2) + \cos(\omega/2) \sin(\omega/2)}{\cos^2(\omega/2)} \\ &= \frac{z}{T_s} \frac{\sin(\omega/2)}{\cos(\omega/2)} = \frac{z}{T_s} \tan\left(\frac{\omega}{2}\right) \end{aligned}$$

$$\Omega = \frac{z}{T_s} \tan\left(\frac{\omega}{2}\right) \quad \left( \text{NOTE! For small } \omega, \Omega \approx \omega/T_s \right)$$

→ And

$$\omega = 2 \tan^{-1} \left( \frac{\Omega T_s}{z} \right); \quad -\pi < \omega < \pi$$

This is the "warping" found in Bilinear Tx.

### ③ Pre-warped Bilinear Transform

By adjusting  $H_c(s)$  we can correct for frequency warping AT ONE frequency.

Consider an  $N$ -th order Butterworth.

$$|H_c(\Omega)|^2 = \frac{1}{1 + \left(\frac{\Omega}{\Omega_c}\right)^{2N}}$$

where  $\Omega_c$  is a constant = cutoff frequency in rad/s if we designed this with Bilinear transform, we know  $\Omega = \frac{2}{T_s} \tan(\omega/2)$ , so the frequency response of the digital filter is

$$|H(\omega)|^2 = |H_c(\Omega)|^2 \Big|_{\Omega = \frac{2}{T_s} \tan(\frac{\omega}{2})} = \frac{1}{1 + \left(\frac{\frac{2}{T_s} \tan(\frac{\omega}{2})}{\Omega_c}\right)^{2N}}$$

The cutoff frequency occurs at

$$\Omega_c = \frac{2}{T_s} \tan\left(\frac{\omega}{2}\right) \quad \text{or} \quad \omega = 2 \tan^{-1}\left(\frac{\Omega_c T_s}{2}\right)$$

When we would have expected it at  $\omega = \Omega_c T_s$ ,

So we pre-warp the analog filter such that:

$$\rightarrow \Omega_c' = \frac{2}{T_s} \tan\left(\frac{\Omega_c T_s}{2}\right)$$

Then.

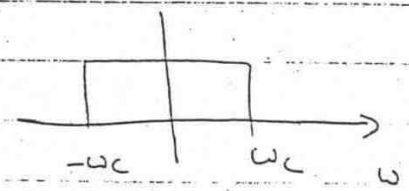
$$|H(\omega)|^2 = |H_c(\Omega)|^2 \Big|_{\Omega = \frac{2}{T_s} \tan(\frac{\omega}{2})} = \frac{1}{1 + \left(\frac{\frac{2}{T_s} \tan(\frac{\omega}{2})}{\frac{2}{T_s} \tan(\frac{\Omega_c T_s}{2})}\right)^{2N}}$$

So  $\rightarrow$  Change the analog filter cutoff frequency so the digital filter cutoff is correct ( $\omega = \Omega_c T_s$ )

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# FIR Design By Windowing

Suppose! you want to approximate  
an IDEAL FILTER (LOWPASS)

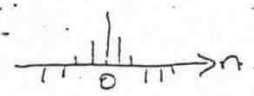


Problem:

$$h_d[n] = \frac{\sin(\omega_c n)}{\pi n}$$

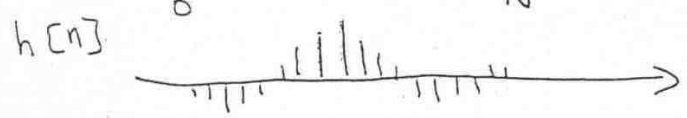
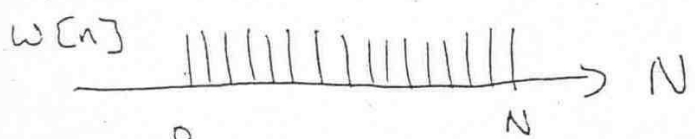
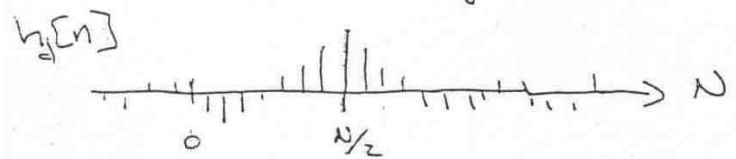
IS NON CAUSAL.

desired impulse resp.



So

Assume THAT you want M-point FIR  
Approximation; Now: delay  $h[n]$  by  
 $M/2$  to get "more CAUSAL" (same as multiplying by  
 $e^{-j\omega M/2}$  in FREQ. Domain)



ONE APPROACH  
TO FIR. is to  
Simply truncate.

But what is the effect of this truncation  
in FREQUENCY Domain?



$$\mathcal{F}\{h_d[n] w[n]\} = \mathcal{F}\{h[n]\}$$

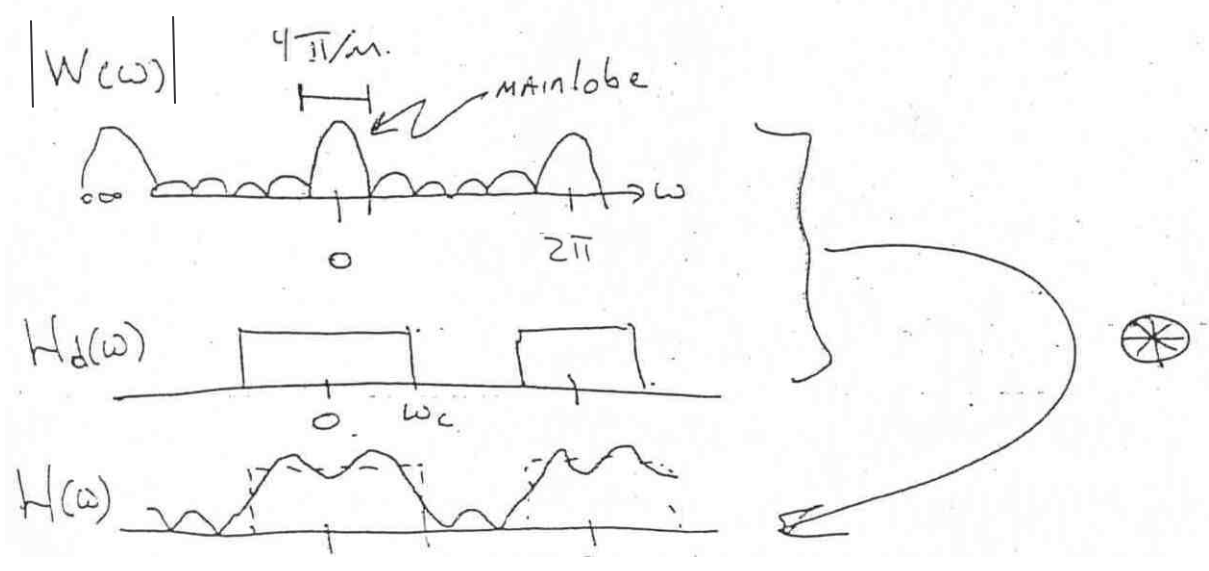
$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} H_d(\alpha) W(\omega - \alpha) d\alpha$$

So the resulting filter is the convolution of the desired response  $H_d(\omega)$  with the DTFT of the window function  $w[n]$ .

In our case  $w[n] = \begin{cases} 1 & 0 \leq n \leq M-1 \\ 0 & \text{otherwise} \end{cases}$

So

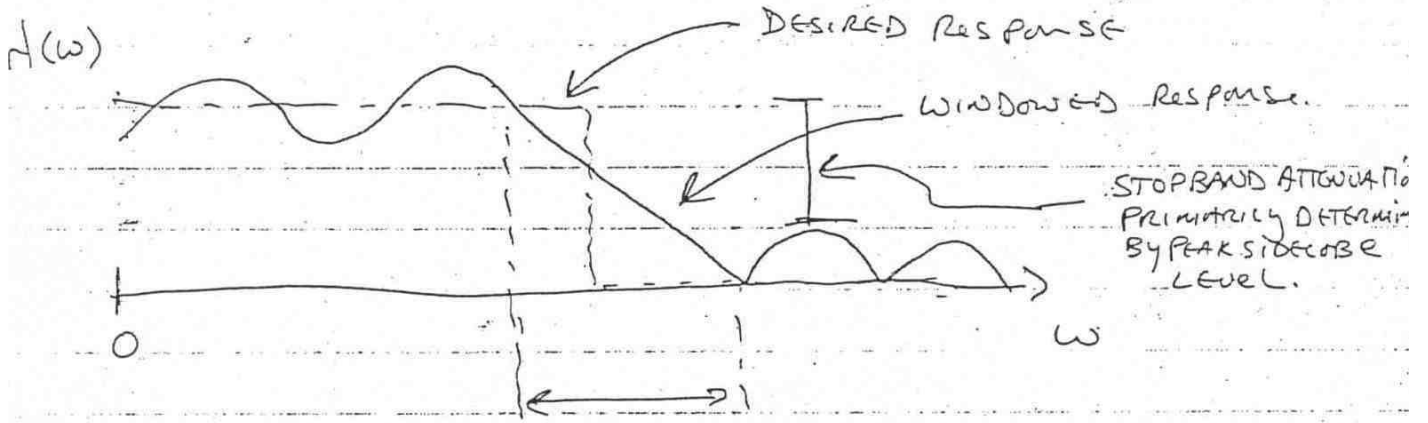
$$W(\omega) = \frac{\sin(\omega M/2)}{\sin(\omega/2)} e^{-j\omega(M-1)/2}$$



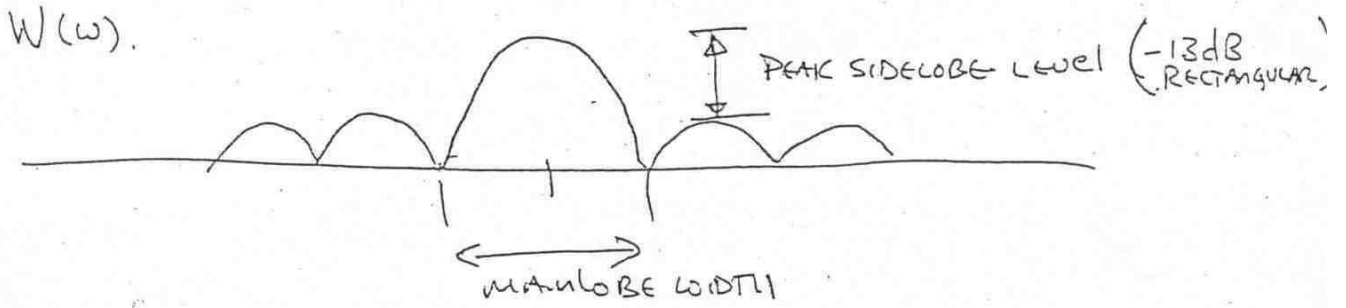
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So:

We can see:



WIDTH OF TRANSITION REGION - PRIMARILY AFFECTED BY MAINLOBE WIDTH.



So

Choice of different window functions leads to different SPECTRAL TRADEOFFS.

→ Generally LARGER TRANSITION REGION. ⇒ lower "side lobes"

**Page 468 TABLE 7. OPPG10.10.1**

Other windows

Figure 7.29. ~~fast~~

# FIR FILTER WINDOWS

## RECTANGULAR

$$w[n] = \begin{cases} 1 & ; 0 \leq n \leq N_0 \\ 0 & ; \text{otherwise} \end{cases}$$

Where  $N_0 = \text{window length}$ .

## Bartlett (triangular)

$$w[n] = \begin{cases} 2n/N_0 & ; 0 \leq n \leq N_0/2 \\ 2 - 2n/N_0 & ; N_0/2 \leq n < N_0 \\ 0 & ; \text{otherwise} \end{cases}$$

## HANNING

$$w[n] = \begin{cases} \frac{1 - \cos(2\pi n/N_0)}{2} & ; 0 \leq n \leq N_0 \\ 0 & ; \text{otherwise} \end{cases}$$

## HAMMING

$$w[n] = \begin{cases} .54 - .46 \cos\left(\frac{2\pi n}{N_0}\right) & ; 0 \leq n \leq N_0 \\ 0 & ; \text{otherwise} \end{cases}$$

## Blackman

$$w[n] = \begin{cases} .42 - .5 \cos\left(\frac{2\pi n}{N_0}\right) + .08 \cos\left(\frac{4\pi n}{N_0}\right) & \\ 0 & \text{otherwise.} \end{cases}$$

<u>FILTER</u>	<u>PEAK SIDELobe</u>	<u>MAINLOBE WIDTH</u>
RECT.	-13 dB	$\approx 4\pi/N_0$
BARTLETT	-26 dB	$8\pi/N_0$
HANNING	-30 dB	$8\pi/N_0$
HAMMING	-40 dB	$8\pi/N_0$
BLACKMAN	-57 dB.	$12\pi/N_0$



# Filter Architecture

$$\sum_{k=0}^N a_k y[n-k] = \sum_{k'=0}^M b_{k'} x[n-k']$$

$$Z \Rightarrow Y(z) \sum_{k=0}^N a_k z^{-k} = X(z) \sum_{k'=0}^M b_{k'} z^{-k'}$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k'=0}^M b_{k'} z^{-k'}}{\sum_{k=0}^N a_k z^{-k}}$$

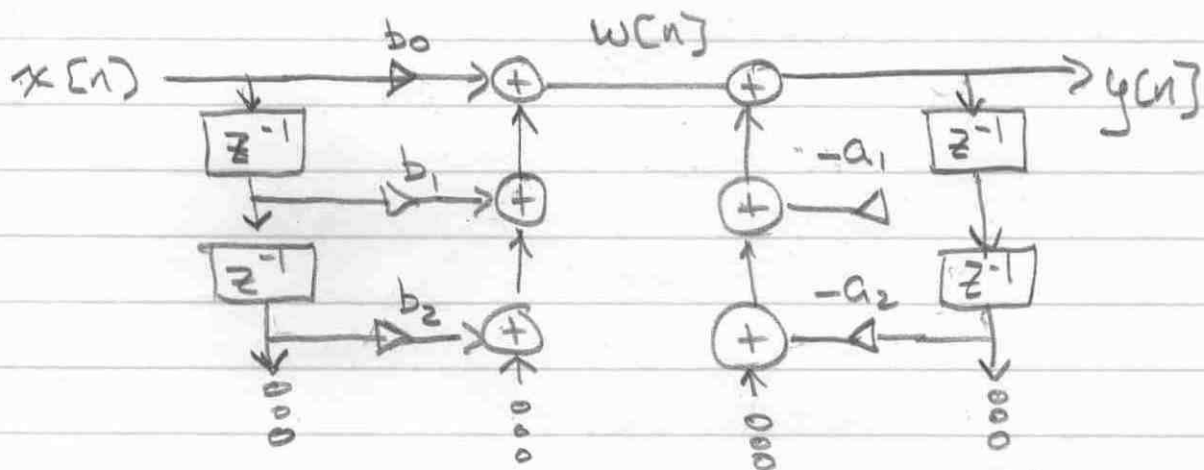
Generally  $a_0 = 1$

$$H(z) = \frac{\sum_{k'=0}^M b_{k'} z^{-k'}}{1 + \sum_{k=1}^N a_k z^{-k}} = \frac{N(z)}{D(z)}$$

REWRITING:

$$y[n] = -a_1 y[n-1] - a_2 y[n-2] \dots + b_0 x[n] + b_1 x[n-1] \dots$$

$$Y(z) = -a_1 z^{-1} Y(z) - a_2 z^{-2} Y(z) \dots + b_0 X(z) + b_1 z^{-1} X(z) \dots$$

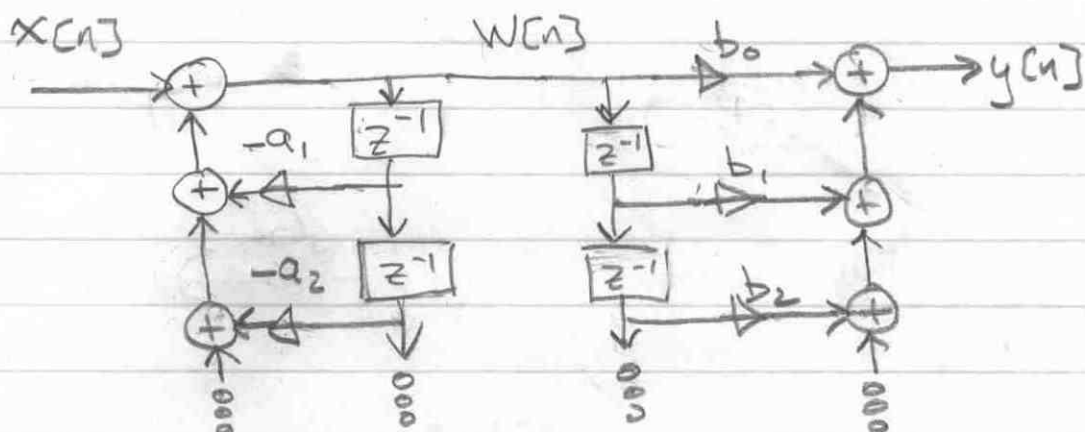


$$W(z) = X(z)N(z)$$

$$Y(z) = W(z)/D(z) = X(z)N(z)/D(z)$$

# FILTER ARCHITECTURES, OTHER FORMS

## Alternate Architecture

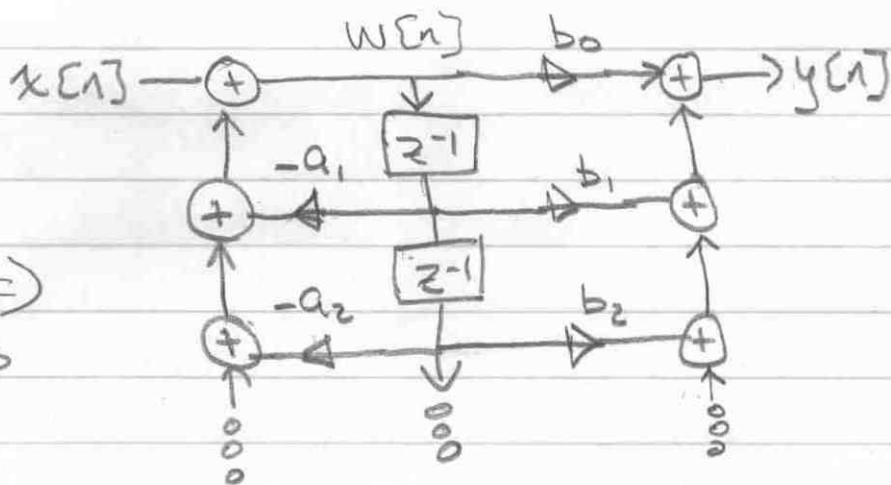


ABOVE  $W(z) = X(z)/D(z)$

$$Y(z) = W(z)N(z) = X(z)N(z)/D(z)$$

ESSENTIALLY THE ABOVE INTERCHANGES  
THE ORDER OF THE  $N(z)$  AND  $1/D(z)$   
SECTIONS OF THE FILTER

ABOVE REDRAWN



USES  
LESS  $\Rightarrow$   
REGISTERS



Misc Stuff

## Butterworth Filters

$$|H_c(\omega)|^2 = \frac{1}{1 + (s/j\omega_c)^{2N}}$$

- N = order of filter
- 1/2 power point @  $s = j\omega_c$

Poles of  $|H_c(\omega)|^2$  AT:

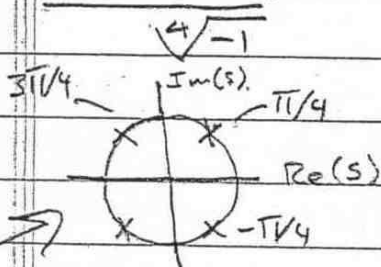
$$(s/j\omega_c)^{2N} = -1$$

$$(s/\omega_c)^{2N} = - (j)^{2N} = -(-1)^N$$

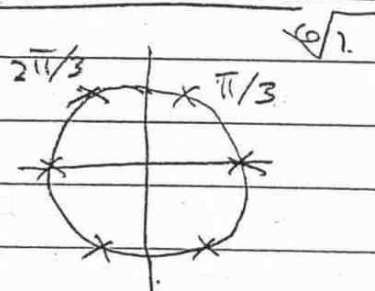
so for N odd,  $s/\omega_c = \sqrt[2N]{1}$   
 $\nearrow$  2N roots of 1 on unit circle

N even  $s/\omega_c = \sqrt[2N]{-1}$

For N=2 (2<sup>nd</sup> order)



For N=3



SELECT STABLE poles (left)

$$H_c(s) = \frac{1}{(s/\omega_c - e^{j3\pi/4})(s/\omega_c - e^{-j3\pi/4})} = \frac{\omega_c^2}{s^2 + \sqrt{2}\omega_c s + \omega_c^2}$$

2<sup>ND</sup> ORDER Butterworth

① Impulse Invariance

$$H_c(s) = \frac{1}{(s/\Omega_c e^{j3\pi/4})(s/\Omega_c e^{-j3\pi/4})}$$

PARTIAL FRAC. EXPANSION

$$= \Omega_c \left( \frac{-\delta/\sqrt{2}}{s - \Omega_c e^{-j3\pi/4}} + \frac{\delta/\sqrt{2}}{s - \Omega_c e^{j3\pi/4}} \right)$$

$$\text{So } H(z) = T_s \Omega_c \left( \frac{-\delta/\sqrt{2}}{1 - e^{j\Omega_c T_s e^{-j3\pi/4}} z^{-1}} + \frac{\delta/\sqrt{2}}{1 - e^{j\Omega_c T_s e^{j3\pi/4}} z^{-1}} \right)$$

Since  $\frac{A_k}{s - s_k} \Rightarrow \frac{A_k T_s}{1 - e^{s_k T_s} z^{-1}}$

② Bilinear

$$H(z) = \frac{\Omega_c^2}{s^2 + \sqrt{2} \Omega_c s + \Omega_c^2}$$

$$s = \frac{z}{T_s} \left( \frac{z-1}{z+1} \right)$$

③ Prewarp Bilinear

Suppose  $F_s = 8000 \text{ 1/s}$   $T_s = 1/8000$   $\Omega_c = 1000 \text{ Hz} \cdot 2\pi$   
 First Prewarp

$$|H_p(s)|^2 = \frac{1}{1 + \left( \frac{s}{\frac{\Omega_c T_s}{2} \tan\left(\frac{\Omega_c T_s}{2}\right)} \right)^2} = \frac{1}{1 + \left( \frac{s}{\frac{1}{2} (1055) 2\pi} \right)^2}$$

$$\text{So } H_p(s) = \frac{\Omega_c^2}{s^2 + \sqrt{2} \Omega_c s + \Omega_c^2} \quad \Omega_c = (1055) 2\pi$$

$$H(z) = H_p(s) \quad \left| \quad s = \frac{z}{T_s} \left( \frac{z-1}{z+1} \right) \right.$$



## Chebyshev Filters

$$|H(s)|^2 = \frac{1}{1 + \epsilon^2 C_n^2(s/\omega_c)}$$

$\epsilon^2$  SETS PASSBAND RIPPLE

PASSBAND VARIES FROM  $1/(1+\epsilon^2)$  TO 1

$C_n(\cdot)$  IS DEFINED RECURSIVELY

$$C_n(x) = 2x C_{n-1}(x) - C_{n-2}(x)$$

Where

$$C_0(x) = 1$$

$$C_1(x) = x$$

$$C_2(x) = 2x^2 - 1$$

$$C_3(x) = 4x^3 - 3x$$

$$C_4(x) = 8x^4 - 8x^2 + 1$$

### Notes

1.  $C_n(1) = 1$  FOR ALL  $C_n(\cdot)$

2.  $|C_n(0)| = 1$  OR  $0$ .